

KEY DECODING

OVERVIEW

The routine described in this application note, "key_decoding," determines the key ID (look-up table index value) each time a key is pressed.

Table 3-1. Arguments and Register Allocations for "key_decoding"

Argument	Addressing	Description
keyinf	Register (bit-wise)	This one-bit flag indicates whether or not a key is valid.
KeyValue	Working register	This working register is used to save the key index value that is used to jump to the key service routine for each input.
Buf	Working register	This working register is used to save the key index code (00H –1FH) that is manipulated by key position.
r0, r1	Working registers r0,r1	These working registers are used to store the start address of each key service handler.
r2, r3	Working registers r2,r3	These working registers are used to read out the start address of the key service handler from the look-up table "keydecidx".

Programming Guidelines

- The key_decoding routine is accessed by the main routine. The main routine has to call key_decoding before key_scan can be executed.
 - Because key_decoding determines key identification by manipulating oldkeyin and oldkeyout register values, changing the oldkeyin and oldkeyout value can cause the main key decoding operation to execute. The key_scan subroutine is always located in the key service program at an address *before* the start of the key_decoding subroutine.
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Basic Operation

1. First, test if the flag 'keyinf' in the main routine is High level. If it is not High, return to the main routine.
2. Otherwise, clear the keyinf flag and calculate the start address of the key service handler, as follows:
 - a. Convert the key output data values FEH, FDH, FBH, F7H, EFH, DFH, BFH, and 7FH to the corresponding indexed values — 0, 1, 2, 3, 4, 5, 6, and 7, respectively.
 - b. Add the indexed value by some weighted value that is obtained by key input data. The binary input data values 0000 0110B, 0000 0101B, and 0000 0011B have the weighted values 0H, 08H, and 10H, respectively.
 - c. The result of steps 'a' and 'b' becomes the key identification code (00H–1FH).
 - d. By manipulating the key ID code and the look-up table for the key service routine's entry, read out the start address of each key service routine:
 - Because the start address of the key service routine has a 2-byte length, multiply the key ID code by two.
 - Add the start of address from the key decode look-up table.
 - Read the key service address from the preceding action.
3. Jump to the appropriate key service routine.

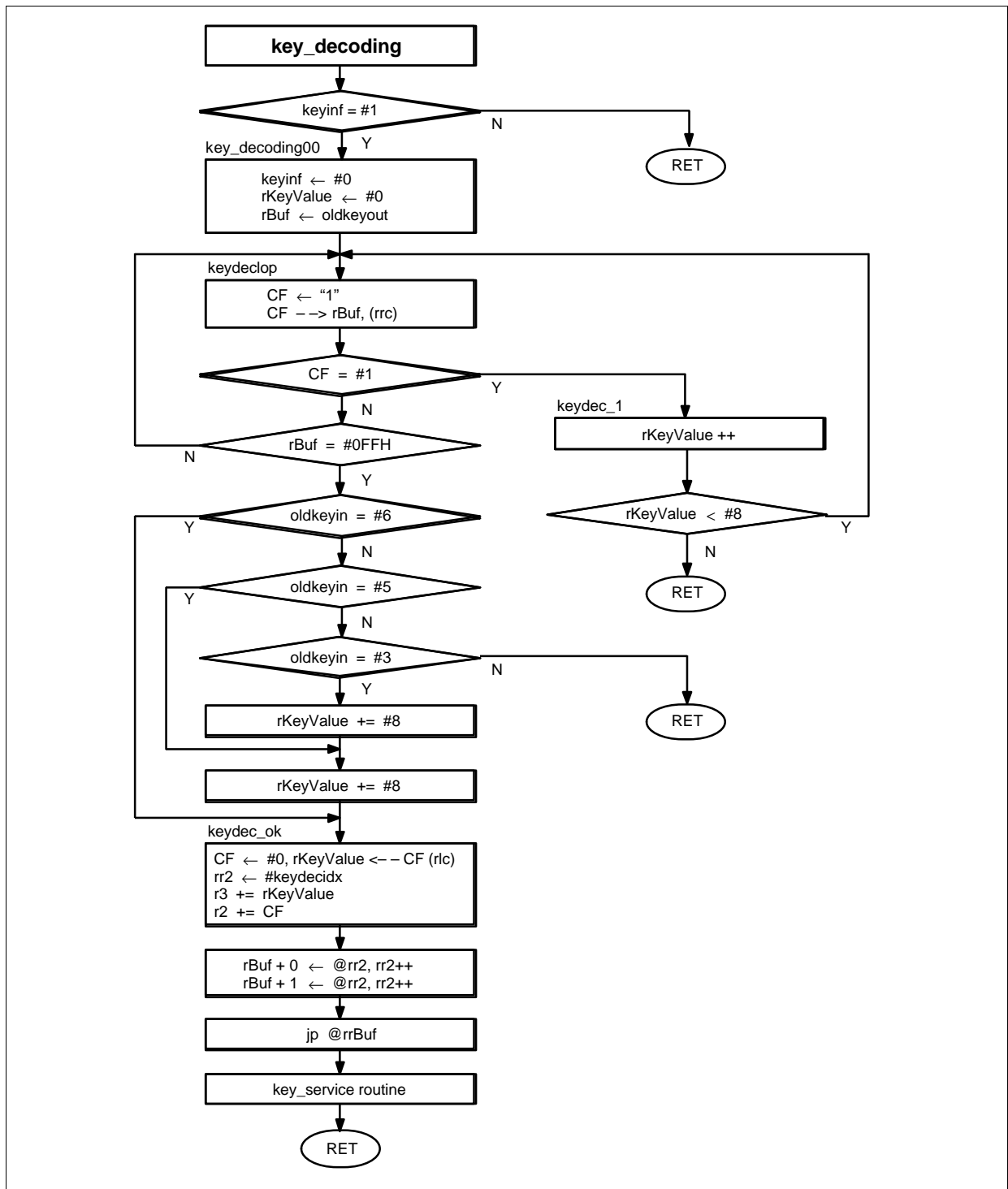


Figure 3-1. Program Flowchart for "key_decoding"

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*===== Key Decoding Routine =====
*=====
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keystrb1:

SOURCE CODE FOR KEY DECODING SUBROUTINE (Cont.)

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keydec_ok:
                                ; Keyvalue ← key ID code (0–23)
                                ;
                                ; Multiply by two because Jump address to key service
                                ; routine has a 2-byte length
                                ; Adjust the pointer of key function
    rcf      cf
    rlc      rKeyValue
    ldw      rr2,#keydecidx
    add      r3,rKeyValue
    adc      r2,#0H
    ldci     rBuf,@rr2
    ldci     rBuf+1,@rr2
    jp       @rrBuf
                                ; Read key function pointer from look-up table in ROM
                                ; Jump to each function key subroutine

;=====
;=== Key Function Service Routine Entry Table ===
;=====

; Key jump address = Base address + Offset (index value)
;                  = keydecidx + key ID code

; Key service routine for each key
                                ; Key ID code

keydecidx:
    dw       keyfnc0, keyfnc1, keyfnc2    ; 00, 01, 02
    dw       keyfnc3, keyfnc4, keyfnc5    ; 03, 04, 05
    dw       keyfnc6, keyfnc7, keyfnc8    ; 06, 07, 08
    dw       keyfnc9, keyfnc10, keyfnc11   ; 09, 0A, 0B
    dw       keyfnc12, keyfnc13, keyfnc14  ; 0C, 0D, 0E
    dw       keyfnc15, keyfnc16, keyfnc17  ; 0F, 10, 11
    dw       keyfnc18, keyfnc19, keyfnc20  ; 12, 13, 14
    dw       keyfnc21, keyfnc22, keyfnc23  ; 15, 16, 17

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